

An adaptive model predictive approach for automated vehicle control in fallback procedure based on virtual vehicle scheme

Xue W, Zheng R, Yang B, Wang Z, Kaizuka T, Nakano K.

Journal of intelligent and connected vehicles

2019; 2(2):67-77

ARTICLE IDENTIFIERS

DOI: 10.1108/JICV-06-2019-0007

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2020204353

pISSN: 2399-9802

eISSN: not available

OCLC ID: 1018199239

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.