

Robust fuzzy sliding mode controller for a skid-steered vehicle subjected to friction variations

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PLoS one

2021; 16(11):e0258909

ARTICLE IDENTIFIERS

DOI: [10.1371/journal.pone.0258909](https://doi.org/10.1371/journal.pone.0258909)

PMID: 34784368

PMCID: PMC8594856

JOURNAL IDENTIFIERS

LCCN: 2006214532

pISSN: not available

eISSN: 1932-6203

OCLC ID: 228234657

CONS ID: not available

US National Library of Medicine ID: 101285081

This article was identified from a query of the SafetyLit database.