

# **A trajectory-tracking controller for improving the safety and stability of four-wheel steering autonomous vehicles**

Liu R, Wei M, Sang N, Wei J.

Transport

2021; 36(2):147-163

## **ARTICLE IDENTIFIERS**

DOI: 10.3846/transport.2021.14291

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1648-4142

eISSN: 1648-3480

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.