

Learning barrier functions with memory for robust safe navigation

Long K, Qian C, Cortés J, Atanasov N.

EEE robotics and automation letters

2021; 6(3):4931-4938

ARTICLE IDENTIFIERS

DOI: 10.1109/LRA.2021.3070250

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2015200129

pISSN: not available

eISSN: 2377-3766

OCLC ID: 903278095

CONS ID: not available

US National Library of Medicine ID: 101680812

This article was identified from a query of the SafetyLit database.