

Incorporating multi-context into the traversability map for urban autonomous driving using deep inverse reinforcement learning

Jung C, Shim DH.

EEE robotics and automation letters

2021; 6(2):1662-1669

ARTICLE IDENTIFIERS

DOI: 10.1109/LRA.2021.3059628

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2015200129

pISSN: not available

eISSN: 2377-3766

OCLC ID: 903278095

CONS ID: not available

US National Library of Medicine ID: 101680812

This article was identified from a query of the SafetyLit database.