

Visualizing the autonomous vehicle's maneuvers - does an ecological interface help to increase the hedonic quality and safety?

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Transportation research part F: traffic psychology and behaviour
2021; 79:11-22

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trf.2021.03.005

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 98646718

pISSN: 1369-8478

eISSN: 1873-5517

OCLC ID: 39912222

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.