

Calibration and evaluation of the Responsibility-Sensitive Safety model of autonomous car-following maneuvers using naturalistic driving study data

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Transportation research part C: emerging technologies
2021; 123:e102988

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trc.2021.102988

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 93640664

pISSN: 0968-090X

eISSN: 1879-2359

OCLC ID: 27960434

CONS ID: sn 93020242

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.