

Modeling and control using connected and automated vehicles with chained asymmetric driver behavior under stop-and-go oscillations

Srivastava A, Chen D, Ahn S.

Transportation research record

2021; 2675(1):342-355

ARTICLE IDENTIFIERS

DOI: 10.1177/0361198120962494

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 74032372

pISSN: 0361-1981

eISSN: 2169-4052

OCLC ID: 01259379

CONS ID: not available

US National Library of Medicine ID: 101481512

This article was identified from a query of the SafetyLit database.