

Adaptive resilient event-triggered control design of autonomous vehicles with an iterative single critic learning framework

Zhang K, Su R, Zhang H, Tian Y.

IEEE transactions on neural networks and learning systems

2021; ePub(ePub):ePub

ARTICLE IDENTIFIERS

DOI: 10.1109/TNNLS.2021.3053269

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2011200425

pISSN: 2162-237X

eISSN: 2162-2388

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: 101616214

This article was identified from a query of the SafetyLit database.