

Assisting operators in heavy industrial tasks: on the design of an optimized cooperative impedance fuzzy-controller with embedded safety rules

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Frontiers in robotics and AI

2019; 6:e75

ARTICLE IDENTIFIERS

DOI: 10.3389/frobt.2019.00075

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2015263051

pISSN: not available

eISSN: 2296-9144

OCLC ID: 884073051

CONS ID: not available

US National Library of Medicine ID: 101749350

This article was identified from a query of the SafetyLit database.