

# **A proof-of-concept field experiment on cooperative lane change maneuvers using a prototype connected automated vehicle testing platform**

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Journal of intelligent transportation systems: technology, planning, and operations  
2021; 25(1):77-92

## **ARTICLE IDENTIFIERS**

DOI: 10.1080/15472450.2020.1775085

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1547-2450

eISSN: 1547-2442

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.