

Deep reinforcement learning based left-turn connected and automated vehicle control at signalized intersection in vehicle-to-infrastructure environment

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Information (Basel)

2020; 11(2):e77

ARTICLE IDENTIFIERS

DOI: 10.3390/info11020077

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2012254624

pISSN: not available

eISSN: 2078-2489

OCLC ID: 701806047

CONS ID: not available

US National Library of Medicine ID: 101703749

This article was identified from a query of the SafetyLit database.