

# **Human-like obstacle avoidance trajectory planning and tracking model for autonomous vehicles that considers the river's operation characteristics**

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Sensors (Basel)

2020; 20(17):e4821

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/s20174821

PMID: 32858979

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.