

Unexpected collision avoidance driving strategy using deep reinforcement learning

Kim M, Lee S, Lim J, Choi J, Kang SG.

IEEE access : practical innovations, open solutions
2020; 8:17243-17252

ARTICLE IDENTIFIERS

DOI: 10.1109/ACCESS.2020.2967509

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2012200491

pISSN: not available

eISSN: 2169-3536

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.