

## **An improved vehicle-pedestrian near-crash identification method with a roadside LiDAR sensor**

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Journal of safety research

2020; 73:211-224

### **ARTICLE IDENTIFIERS**

DOI: 10.1016/j.jsr.2020.03.006

PMID: 32563396

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: 78009062

pISSN: 0022-4375

eISSN: 1879-1247

OCLC ID: 01800052

CONS ID: not available

US National Library of Medicine ID: 1264241

This article was identified from a query of the SafetyLit database.