

# **A universal and reconfigurable stability control methodology for articulated vehicles with any configurations**

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IEEE transactions on vehicular technology

2020; 69(4):3748-3759

## **ARTICLE IDENTIFIERS**

DOI: 10.1109/TVT.2020.2973082

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0018-9545

eISSN: 1939-9359

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.