## Reliable road scene interpretation based on ITOM with the integrated fusion of vehicle and lane tracker in dense traffic situation

Jeong J, Yoon YH, Park JH. Sensors (Basel) 2020; 20(9):e2457

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/s20092457

PMID: 32357432 PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 2002242115 pISSN: not available eISSN: 1424-8220 OCLC ID: 47250782 CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.