

A distributed strategy for cooperative autonomous robots using pedestrian behavior for multi-target search in the unknown environment

Shi H, Li J, Li Z.

Sensors (Basel)

2020; 20(6):e1606

ARTICLE IDENTIFIERS

DOI: 10.3390/s20061606

PMID: 32183107

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.