

## **A novel roll and pitch estimation approach for a ground vehicle stability improvement using a low cost IMU**

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Sensors (Basel)

2020; 20(2):e340

### **ARTICLE IDENTIFIERS**

DOI: 10.3390/s20020340

PMID: 31936080

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.