

# **Model predictive control for integrated lateral stability, traction/braking control, and rollover prevention of electric vehicles**

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Vehicle system dynamics

2020; 58(1):49-73

## **ARTICLE IDENTIFIERS**

DOI: 10.1080/00423114.2019.1585557

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0042-3114

eISSN: 1744-5159

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.