

Optimal control of brakes and steering for autonomous collision avoidance using modified Hamiltonian algorithm

Gao Y, Gordon T, Lidberg M.

Vehicle system dynamics

2019; 57(8):1224-1240

ARTICLE IDENTIFIERS

DOI: 10.1080/00423114.2018.1563706

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 0042-3114

eISSN: 1744-5159

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.