

Novel straight road driving control of power assisted wheelchair based on disturbance estimation of right and left wheels

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IEEJ transactions on industry applications

2006; 126(6):764-770

ARTICLE IDENTIFIERS

DOI: unavailable

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 0913-6339

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.