

Fully autonomous vehicles: analyzing transportation network performance and operating scenarios in the Greater Toronto Area, Canada

Kloostera B, Roorda MJ.

Transportation planning and technology

2019; 42(2):99-112

ARTICLE IDENTIFIERS

DOI: 10.1080/03081060.2019.1565159

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 0308-1060

eISSN: 1029-0354

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.