

Integrated cooperative adaptive cruise and variable speed limit controls for reducing rear-end collision risks near freeway bottlenecks based on micro-simulations

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IEEE transactions on intelligent transportation systems
2017; 18(11):3157-3167

ARTICLE IDENTIFIERS

DOI: 10.1109/TITS.2017.2682193

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1524-9050

eISSN: 1558-0016

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.