

## **An innovative algorithm to estimate risk optimum path for unmanned aerial vehicles in urban environments**

Primatesta S, Cuomo LS, Guglieri G, Rizzo A.

Transportation research procedia

2018; 35:44-53

### **ARTICLE IDENTIFIERS**

DOI: 10.1016/j.trpro.2018.12.006

PMID: unavailable

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 2352-1465

eISSN: not available

OCLC ID: 893979151

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.