

# **Investigating pedestrian suggestions for external features on fully autonomous vehicles: a virtual reality experiment**

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Transportation research part F: traffic psychology and behaviour

2018; 59:135-149

## **ARTICLE IDENTIFIERS**

DOI: 10.1016/j.trf.2018.08.016

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 98646718

pISSN: 1369-8478

eISSN: 1873-5517

OCLC ID: 39912222

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.