

# **Optimizing driver acceptance and objective benefit using Predictive Collision Warning as an example**

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VDI Berichte

2006; 2006(1960):553-562

## **ARTICLE IDENTIFIERS**

DOI: unavailable

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 65000224 //r89

pISSN: 0083-5560

eISSN: not available

OCLC ID: 02692629

CONS ID: sn 82004550

US National Library of Medicine ID: 100970438

This article was identified from a query of the SafetyLit database.