

# **Improving lateral dynamic of vehicle using direct yaw moment controller by differential brake torques based on quantitative feedback theory**

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Scientia Iranica

2017; 24(2):662-672

## **ARTICLE IDENTIFIERS**

DOI: unavailable

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 00251122

pISSN: 1026-3098

eISSN: not available

OCLC ID: 43453436

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.