

Improvement of LQR active anti-roll control of a single-unit heavy vehicle by means of a trained artificial neuronal network

Babesse S, Ameddah D.

International journal of vehicle safety

2016; 9(2):166-179

ARTICLE IDENTIFIERS

DOI: 10.1504/IJVS.2016.079657

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2010273103

pISSN: 1479-3105

eISSN: 1479-3113

OCLC ID: 71284552

CONS ID: not available

US National Library of Medicine ID: 101512599

This article was identified from a query of the SafetyLit database.