

Dual MIMU pedestrian navigation by inequality constraint Kalman filtering

Shi W, Wang Y, Wu Y.

Sensors (Basel)

2017; 17(2):s17020427

ARTICLE IDENTIFIERS

DOI: 10.3390/s17020427

PMID: 28241448

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.