

Identification of an optimum control algorithm to reject unwanted yaw effect on wheeled armored vehicle due to the recoil force

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Advances in mechanical engineering

2017; 9(1):e1687814016683350

ARTICLE IDENTIFIERS

DOI: 10.1177/1687814016683350

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2010205558

pISSN: 1687-8132

eISSN: 1687-8140

OCLC ID: 321528428

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.