

Model-predictive-control-based novel anti-skid method for electric vehicles using the wheel acceleration and the motor torque

Liu X, Li M, Xu M.

Proceedings of the Institution of Mechanical Engineers, Part D: Journal of automobile engineering

2016; 230(13):1780-1790

ARTICLE IDENTIFIERS

DOI: 10.1177/0954407015623895

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 89645606

pISSN: 0954-4070

eISSN: 2041-2991

OCLC ID: 19686979

CONS ID: sn 89038357

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.