

# **A novel robot for imposing perturbations during overground walking: mechanism, control and normative stepping responses**

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Journal of neuroengineering and rehabilitation

2016; 13(1):e55

## **ARTICLE IDENTIFIERS**

DOI: 10.1186/s12984-016-0160-7

PMID: 27287551

PMCID: PMC4903006

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: not available

eISSN: 1743-0003

OCLC ID: 56732778

CONS ID: not available

US National Library of Medicine ID: 101232233

This article was identified from a query of the SafetyLit database.