

Segmentation of vehicle detector data for improved k-nearest neighbours-based traffic flow prediction

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IET intelligent transport systems

2014; 9(3):264-274

ARTICLE IDENTIFIERS

DOI: 10.1049/iet-its.2013.0164

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1751-956X

eISSN: 1751-9578

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.