

Vision-based human tracking control of a wheeled inverted pendulum robot

Ye W, Li Z, Yang C, Sun J, Su CY, Lu R.

IEEE transactions on cybernetics

2015; 46(11):2423-2434

ARTICLE IDENTIFIERS

DOI: 10.1109/TCYB.2015.2478154

PMID: 26441461

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2012200557

pISSN: 2168-2267

eISSN: 2168-2275

OCLC ID: 795360073

CONS ID: not available

US National Library of Medicine ID: 101609393

This article was identified from a query of the SafetyLit database.