

4D trajectory estimation for air traffic control automation system based on hybrid system theory

Tang XM, Han YX.
Promet
2012; 24(2):91-98

ARTICLE IDENTIFIERS

DOI: 10.7307/ptt.v24i2.280
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available
pISSN: 0353-5320
eISSN: 1848-4069
OCLC ID: 455276237
CONS ID: not available
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.