

# **Fusing LIDAR, camera and semantic information: A context-based approach for pedestrian detection**

Premebida C, Nunes U.

International journal of robotic research

2013; 32(3):371-384

## **ARTICLE IDENTIFIERS**

DOI: 10.1177/0278364912470012

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 82647259

pISSN: 0278-3649

eISSN: 1741-3176

OCLC ID: 7793158

CONS ID: sn 81002024

US National Library of Medicine ID: 101511318

This article was identified from a query of the SafetyLit database.