

Simultaneous vehicle-handling and path-tracking improvement using adaptive dynamic surface control via a steer-by-wire system

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Proceedings of the Institution of Mechanical Engineers, Part D: Journal of automobile engineering

2013; 227(3):345-360

ARTICLE IDENTIFIERS

DOI: 10.1177/0954407012453240

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 89645606

pISSN: 0954-4070

eISSN: 2041-2991

OCLC ID: 19686979

CONS ID: sn 89038357

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.