

**Proposal for a new localisation method using tightly coupled integration based on a precise estimation of trajectory from GPS Doppler**

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Vehicle system dynamics

2012; 50(6):987-1000

**ARTICLE IDENTIFIERS**

DOI: 10.1080/00423114.2011.602697

PMID: unavailable

PMCID: not available

**JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0042-3114

eISSN: 1744-5159

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.