

**Design of robust-stable and quadratic finite-horizon optimal controllers with low trajectory sensitivity for uncertain active suspension systems**

Chen SH, Chou JH, Zheng LA, Lin SK.

Vehicle system dynamics

2010; 48(8):945-965

**ARTICLE IDENTIFIERS**

DOI: 10.1080/00423110903243174

PMID: unavailable

PMCID: not available

**JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0042-3114

eISSN: 1744-5159

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.