

Monocular Camera/IMU/GNSS Integration for Ground Vehicle Navigation in Challenging GNSS Environments

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Sensors (Basel)

2012; 12(3):3162-3185

ARTICLE IDENTIFIERS

DOI: 10.3390/s120303162

PMID: 22736999

PMCID: PMC3376587

JOURNAL IDENTIFIERS

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.