

CLARK: a heterogeneous sensor fusion method for finding lanes and obstacles

Beauvais M, Lakshmanan S.
Image and vision computing
2000; 18(5):397-413

ARTICLE IDENTIFIERS

DOI: 10.1016/S0262-8856(99)00035-9
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 83646419
pISSN: 0262-8856
eISSN: not available
OCLC ID: 09320255
CONS ID: not available
US National Library of Medicine ID: 101151810

This article was identified from a query of the SafetyLit database.