

A fail-safe dual channel robot control for surgery applications

Laible U, Burger T, Pritschow G.

Safety science

2004; 42(5):423-436

ARTICLE IDENTIFIERS

DOI: unavailable

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 91640944

pISSN: 0925-7535

eISSN: 1879-1042

OCLC ID: 23966897

CONS ID: sn 91-38208

US National Library of Medicine ID: 9114980

This article was identified from a query of the SafetyLit database.