

## **Use of the Crash Prevention Boundary Methodology to Describe the Performance of Adaptive Cruise Control Systems**

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Proceedings: International Technical Conference on the Enhanced Safety of Vehicles 2005; 2005:9p

### **ARTICLE IDENTIFIERS**

DOI: unavailable

PMID: unavailable

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: not available

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

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